

# Image Restoration based on A Hybrid Model by Alternating Direction Optimization

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In order to better preserve the edge features and also refrain them from the staircasing effect in smooth regions, this paper investigates a hybrid model for restoring the blurred images with additive Gaussian noise and an effective iterative scheme based on alternating direction method is employed to solve the minimization problem suggested by us with two regularization terms. Numerical experiments demonstrate that the hybrid scheme proposed by us is superior to the model with only one regularization term in respect of image restoration quality.

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## 1. Introduction

The image denoising and deblurring plays a significant role in the field of image processing. Finding the unknown original image u from an observed image  $u_0$  can be modeled as follows :

$$\min_{u} \left\| Ku - u_0 \right\|_2^2 + \lambda \Phi(u) \tag{1.1}$$

where K is a bounded linear operator,  $\Phi(u)$  denotes a regularization function to overcome the ill-posed property and the regularization parameter  $\lambda > 0$  is used to balance the two terms. In 1992, Rudin, Osher and Fatemi [1] firstly put forward to consider the following *l*-1norm of the gradient of *u* as the regularization scale

$$\min_{u} \|Ku - u_0\|_2^2 + \lambda \|Du\|_1$$
(1.2)

This total variation (TV) restoration model allows for discontinuities and turns out to do better in suppressing noise and handling edges; however, although the TV-based model makes great progress in preserving edges while filtering out noise, the visually unpleasant staircasing effects still emerge in the result images, which can be usually viewed as false edges by some sensitive detection tools. In order to solve this problem, high order partial differential equation based on image restoration methods has been investigated [2-3], for instance, the following LLT smoothing scheme [4]

$$\min_{u} \|Ku - u_0\|_2^2 + \lambda \|D^2 u\|_1$$
(1.3)

These higher order filters succeed in avoiding piecewise constant of the solution, but the edge blur phenomenon still appears. Consequently, some hybrid smoothing methods have been developed [5-6]. Particularly, the total generalized variation (TGV) and a tensor based high order regularization scheme demonstrated their superiority when compared with LLT model [7]. A method based on wavelet sparse operator and TV regularization was applied to Poisson noise removal [8]. Li et al. designed an adaptive hybrid denoising model but featured low efficiency [9]. Recently, a learning-based method was proposed to improve the processing quality but it was time-consuming, just like some other learning technologies [10].

Here, we take the following hybrid model into consideration

$$\min_{u} \|Ku - u_0\|_2^2 + \alpha \|Du\|_1 + \beta \|D^2 u\|_1$$
(1.4)

where *K* denotes the blurring operator, gradient operator  $||Du||_1 = \sqrt{u_x^2 + u_y^2}$  and  $||D^2u||_1 = \sqrt{u_{xx}^2 + u_{yy}^2 + u_{yy}^2 + u_{yy}^2}$ . This hybrid regularization strategy can take account of advantages of the two filter terms and cover their shortcomings so as to yield more desired images.

This paper is organized as follows. In Section 2, the numerical algorithm for solving the proposed strategy is introduced; the contrast of the proposed method and the TV-based one by numerical experiments is given in Section 3; finally, the main conclusion is made in Section 4.

#### 2. Iterative Algorithm

Although the hybrid model compromises the merits of the model with only one regularization, the complexity increases the computational difficulties. We introduce the following alternating direction method (ADM) to solve this problem, which stands up to be competitive with the previous and existing algorithms such as TwIST [11], FISTA [12], FTVd[13], etc.

$$u^{k+1} = \arg\min_{u} \|Ku - u_{0}\|_{2}^{2} + \frac{\lambda}{2} \|u - w^{k} + b_{1}^{k}\|_{2}^{2} + \frac{\lambda}{2} \|u - z^{k} + b_{2}^{k}\|_{2}^{2}$$

$$w^{k+1} = \arg\min_{u} \alpha \|Dw\|_{1} + \frac{\lambda}{2} \|u^{k+1} - w^{k} + b_{1}^{k}\|_{2}^{2}$$

$$z^{k+1} = \arg\min_{u} \beta \|D^{2}z\|_{1} + \frac{\lambda}{2} \|u^{k+1} - z + b_{2}^{k}\|_{2}^{2}$$

$$b_{1}^{k+1} = b_{1}^{k} + u^{k+1} - w^{k+1}$$

$$b_{2}^{k+1} = b_{2}^{k} + u^{k+1} - w^{k+1} \qquad (2.1)$$

Clearly, *u* subproblem can be solved exactly, i.e.,

$$u^{k+1} = \left(2K^{T}K + 2\lambda\right)^{-1} \left[2K^{T}u_{0} + \lambda\left(w^{k} - b_{1}^{k}\right) + \lambda\left(z^{k} - b_{2}^{k}\right)\right]$$
(2.2)

The Bregman method suffers from difficulty in dealing with high-order problems, we conformably adopt the Chambolle's dual method [14-15] to solve W and z subproblems.

# Algorithm 1: Alternating direction method to solve the model

Choose: parameters 
$$\alpha, \beta, \lambda$$
 and time step size  $\Delta t$ ;  
Initialization:  $b_1^0 = 0, b_2^0 = 0, p^0 = 0, w^0 = 0, w^0 = u_0, z^0 = u_0$   
While  $\frac{\|u^{k+1} - u^k\|_2}{\|u^k\|_2} > tol$   
 $u^{k+1} = (2K^T K + 2\lambda)^{-1} [2K^T u_0 + \lambda (w^k - b_1^k) + \lambda (z^k - b_2^k)]$   
 $w^{k+1} = u^{k+1} + b_1^k - \frac{\alpha}{\lambda} div (p^{k+1})$   
 $p_{i,j}^{k+1} = \frac{p_{i,j}^k + \Delta t (D(\operatorname{div} p^k - \frac{\lambda}{\alpha} (u^{k+1} + b_1^k)))_{i,j}}{1 + \Delta t \left| D(\operatorname{div} p^k - \frac{\lambda}{\alpha} (u^{k+1} + b_1^k))_{i,j} \right|}$   
 $z^{k+1} = u^{k+1} + b_2^k - \frac{\beta}{\lambda} \operatorname{div}^2 (q^{k+1})$   
 $q_{i,j}^{k+1} = \frac{q_{i,j}^k - \Delta t (D^2 (\operatorname{div}^2 q^k - \frac{\lambda}{\beta} (u^{k+1} + b_2^k)))_{i,j}}{1 + \Delta t \left| D^2 (\operatorname{div}^2 q^k - \frac{\lambda}{\beta} (u^{k+1} + b_2^k))_{i,j} \right|}$   
 $b_1^{k+1} = b_1^k + u^{k+1} - w^{k+1}$ 

-End

## **3. Numerical Results**

The following signal noise ratio (SNR) is adopted,

$$SNR = 10 \ \log_{10} \frac{\left\| u - \overline{u} \right\|_{2}^{2}}{\left\| n - \overline{n} \right\|_{2}^{2}}$$
(3.1)

where  $u, \overline{u}$  and  $\overline{n}$  stand for the recovered image, the means of  $\overline{u}$  and the noise  $\overline{n}$  respectively.

Fig. 1(a) and Fig. 1(b) show the original "lenna" and the degenerated "lenna" image with SNR=14.55, corrupted by Gaussian noise and blurred by 3 3 Gaussian kernel and standard deviation; 2. Fig. 1(c-e) are recovered images by TV, LLT and our proposed method by 19 outer iterations respectively. The consumption time of our method is about 0.42s as to an image of the size of 256\*256 under Matlab 2009 in our Laptop with 2.9HZ. In the implementation of the algorithm proposed by us, the parameters are set to be  $\alpha = 0.004$ ,  $\beta = 0.0005$ ,  $\lambda = 0.5$  so as to yield more desired results. Generally speaking, the parameter  $\alpha$  is larger than  $\beta$  to save from the over-smoothing and  $\lambda$  can be set around 1. Actually,  $\lambda$  is used to make w and z approximate u, which is not so sensitive to the restoration results because of adding the update variables  $b_1$  and  $b_2$  [16]. The convergence curves of the methods with four different parameters are displayed in Fig. 4. Data 1 denotes the convergence curve of our proposed method with  $\alpha = 0.004, \beta = 0.0005, \lambda = 0.5.$ Data 2 is the convergence of the scheme with  $\alpha = 0.004, \beta = 10^{-10}, \lambda = 0.5$ , which approximates the TV regularization. Data 3 denotes the convergence behavior of the scheme with parameters  $\alpha = 10^{-10}$ ,  $\beta = 0.002$ ,  $\lambda = 0.5$ , which approximates the LLT image restoration scheme. Larger  $\beta$  will results in over-smoothing not only in LLT model but also in our proposed hybrid model. The hybrid model can obtain more desired results.



Figure1: Results by TV-regularization, LLT Model and Our Scheme

Lenna	Degenerated	TV	LLT	Our proposed
SNR	14.55	18.78	18.68	18.96

Table 1: SNR Value of Observed Image and Recovered Images by Different Methods

In comparison of the zoomed partial result image Fig. 2(c) processed by only TVregularization based algorithm with Fig. 2(d) processed by the algorithm proposed by us, we can clearly see that the disgusting staircasing effect emerges in the lenna's check in Fig. 2(c) and dramatically disappears in Fig. 2(d). Fig. 2(d) has more encouraging result and looks more natural. In comparison of the zoomed partial result image Fig. 3(c) processed by LLT model based algorithm with Fig. 3(d) processed by the algorithm proposed by us, we can find the edge preserving ability exceeds the LLT method. Our method has the advantages of both stair-casing reduction and edge-preserving accordingly.



(a) Original Lenna (b) Observed Lenna (c) TV (d) Proposed Method





(a) Original Lenna (b) Observed Lenna (c) LLT (d) Proposed Method





Figure 4: Convergence Curve

## 4. Conclusion

A hybrid regularization method for deblurring and denoising problem is introduced in this paper. In order to overcome the numerical calculation difficulties brought about by the non-smooth high-order hybrid regularization term, the effective alternating direction method is hereby introduced. Simulation experiment results demonstrate that more high-quality reconstruction images are available by our proposed scheme. The images have not only preserved edges and but also avoids staircasing effects.

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