# MBnumerics: Numerical integration of Mellin-Barnes integrals in physical regions 

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We introduce techniques to treat numerically Mellin-Barnes integrals in physical regions, which arise in the need of the computation of Feynman integrals for the electroweak two-loop corrections to the pseudo observables at the Z-boson resonance.

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## 1. Introduction

Our starting point will be the loop-momenta integral representation of a scalar Feynman integral:

$$
\begin{equation*}
G_{L}=\int \prod_{j=1}^{L} \frac{\mathrm{~d}^{D} k_{j}}{i \pi^{D / 2}} \frac{1}{P_{1}^{v_{1}} \ldots P_{N}^{V_{N}}} \tag{1.1}
\end{equation*}
$$

The functions $P_{i}^{v_{i}}$ in the denominator are expressed in terms of the $L$ loop-momenta $k_{l}$ which are not fixed through momentum conservation at each vertex and the $E$ linearly independent external momenta $p_{e}$ :

$$
\begin{equation*}
P_{i}=\left(\sum_{l=1}^{L} a_{i l} k_{l}+\sum_{e=1}^{E} b_{i e} p_{e}\right)^{2}-m_{i}^{2}+i \delta, a_{i l}, b_{i e} \in\{-1,0,1\} \tag{1.2}
\end{equation*}
$$

where the $m_{i}$ denote the masses of the corresponding virtual particles. The $i \delta$ is the Feynman prescription. In the most general case the $P_{i}$ are a linear combination of $N$ linearly independent scalar products depending on the loop-momenta $k_{l}$. The propagator exponents $v_{i}$ are complex variables if not stated otherwise. Within dimensional regularization, $D=4-2 \varepsilon$ denotes the dimension of space-time. As usual $D \neq 4$ is used to regularize infrared or ultraviolet divergences.

Before evaluating these integrals one often applies the Feynman trick:

$$
\begin{equation*}
\frac{(-1)^{v}}{\prod_{j=1}^{N}\left(-P_{j}^{v_{j}}\right)}=\frac{(-1)^{v} \Gamma(v)\left(\prod_{j=1}^{N} \tilde{n}_{j}\right) \delta\left(1-\sum_{j=1}^{N_{G}} x_{j}\right)}{\left(-k_{l}^{\mu} M_{l l^{\prime}} k_{l^{\prime} \mu}+2 k_{l}^{\mu} Q_{l \mu}+J-i \delta\right)^{v}}, \quad v=\sum_{j=1}^{N} v_{j} \tag{1.3}
\end{equation*}
$$

where

$$
\begin{equation*}
M_{l l^{\prime}}=\sum_{j=1}^{N} a_{j l} a_{j l^{\prime}} x_{j} \tag{1.4}
\end{equation*}
$$

is an $L \times L$ symmetric matrix,

$$
\begin{equation*}
Q_{l}^{v}=-\sum_{j=1}^{N} x_{j} a_{j l} \sum_{e=1}^{E} b_{j e} p_{e}^{v} \tag{1.5}
\end{equation*}
$$

is a vector with $L$ components and

$$
\begin{equation*}
J=-\sum_{j=1}^{N} x_{j}\left(\sum_{e=1}^{E} b_{j e} p_{e}^{\mu} \sum_{e^{\prime}=1}^{E} p_{e^{\prime}}^{v} b_{j e^{\prime}} g_{\mu v}-m_{j}^{2}\right) \tag{1.6}
\end{equation*}
$$

where $x_{j}$ are the Feynman parameters introduced with the Feynman trick. The set of Feynman parameters $\left\{x_{1}, \ldots, x_{N_{G}}\right\}$ corresponds to the set of functions $\left\{P_{1}, \ldots, P_{N_{G}}\right\}$ with positive $\left\{v_{1}, \ldots, v_{N_{G}}\right\}$ in Eq.(1.1). The metric tensor is $g_{\mu \nu}=\operatorname{diag}(1,-1, \ldots,-1)$. The $\tilde{n}_{j}$ is defined as:

$$
\tilde{n}_{j} \phi(\vec{x})=\left\{\begin{array}{l}
\int_{\left\{x_{j} \geq 0\right\}} \frac{\mathrm{d} x_{j} x_{j}^{v_{j}-1}}{\Gamma\left(v_{j}\right)} \phi(\vec{x}), \quad v_{j} \neq-m,  \tag{1.7}\\
(-1)^{v_{j}} \phi^{\left(-v_{j}\right)}\left(0, x_{i \neq j}\right), \quad v_{j}=-m,
\end{array} \quad m \in \mathbb{N}_{0}\right.
$$

where $\phi^{\left(-v_{j}\right)}\left(0, x_{i \neq j}\right)$ means to take $\left(-v_{j}\right)$ derivative in $x_{j}$ and then set $x_{j}$ to zero.

The Feynman integral can now be written in the Feynman parameter integral representation:

$$
\begin{equation*}
G_{L}=(-1)^{v} \Gamma(v-L D / 2)\left(\prod_{j=1}^{N} \tilde{n}_{j}\right) \delta\left(1-\sum_{j=1}^{N_{G}} x_{j}\right) \frac{\mathscr{U}(x)^{v-(L+1) D / 2}}{\mathscr{F}(x)^{v-L D / 2}}, \tag{1.8}
\end{equation*}
$$

where

$$
\begin{align*}
\mathscr{U}(x) & =\operatorname{det} M  \tag{1.9}\\
\mathscr{F}(x) & =\mathscr{U}(x)\left(Q_{l}^{\mu} M_{l l^{\prime}}^{-1} Q_{l^{\prime} \mu}+J-i \delta\right) . \tag{1.10}
\end{align*}
$$

From these definitions it follows that the functions $\mathscr{F}(x)$ and $\mathscr{U}(x)$ are homogeneous in the Feynman parameters $x_{i}$. The function $\mathscr{U}(x)$ is of degree $L$ and the function $\mathscr{F}(x)$ is of degree $L+1$. The functions $\mathscr{U}(x)$ and $\mathscr{F}(x)$ are also known as Symanzik polynomials.

### 1.1 Mellin-Barnes integral

Feynman integrals may be infrared and ultraviolet divergent. To treat these integrals in a consistent and automated way two methods are known: The Mellin-Barnes integral approach [1, 2, $3,4,5]$ and the sector decomposition approach $[6,7,8,9,10,11]$.

To derive a Mellin-Barnes integral one will use either the loop-by-loop approach [12] or the global approach [13]. Both techniques apply in their core to the $\mathscr{F}(x)$ and $\mathscr{U}(x)$ functions in Eq. (1.8) the Mellin-Barnes integral master formula:

$$
\begin{equation*}
\frac{1}{(a+b)^{v}}=\int_{-i \infty}^{i \infty} \frac{\mathrm{~d} z}{2 \pi i} \frac{a^{z} b^{-z-v} \Gamma(-z) \Gamma(v+z)}{\Gamma(v)}, \quad|\arg a-\arg b|<\pi \tag{1.11}
\end{equation*}
$$

until the integrations over the Feynman parameters can be all carried out in terms of Euler's Betafunctions:

$$
\begin{equation*}
B(\xi, \chi)=\int_{0}^{\infty} \frac{x^{\xi-1}}{(1+x)^{\xi+\chi}} \mathrm{d} x=\frac{\Gamma(\xi) \Gamma(\chi)}{\Gamma(\xi+\chi)}, \quad \Re e \xi>0, \mathfrak{R} e \chi>0 \tag{1.12}
\end{equation*}
$$

These steps lead to Mellin-Barnes integrands depending on a ratio of Euler's Gamma-functions $\Gamma$ depending on the integration variables $z_{i}$ and some kinematics raised to the powers of $z_{i}$.

As an example we study the Feynman integral in Fig. 1, whose loop-momenta integral representation contains one nontrivial numerator $k_{1} p_{1}$ :

$$
\begin{equation*}
I_{0 \mathrm{~h} 0 \mathrm{w} 14 \mathrm{r}}=\int \frac{\mathrm{d}^{D} k_{1}}{i \pi^{D / 2}} \frac{\mathrm{~d}^{D} k_{2}}{i \pi^{D / 2}} \frac{k_{1} p_{1}}{k_{1}^{2}\left(\left(k_{1}-k_{2}\right)^{2}-M_{Z}^{2}\right) k_{2}^{2}\left(\left(k_{2}+p_{1}\right)^{2}-M_{Z}^{2}\right)\left(k_{1}+p_{1}+p_{2}\right)^{2}} \tag{1.13}
\end{equation*}
$$

and its Mellin-Barnes integral representation is:

$$
\begin{align*}
I_{0 \mathrm{~h} 0 \mathrm{w} 14 \mathrm{r}}= & \int_{-\frac{1}{3}-i \infty}^{-\frac{1}{3}+i \infty} \frac{\mathrm{~d} z_{1}}{2 \pi i} \int_{-\frac{1}{3}-i \infty}^{-\frac{1}{3}+i \infty} \frac{\mathrm{~d} z_{2}}{2 \pi i} \frac{\Gamma\left(-z_{1}\right) \Gamma\left(-z_{2}\right) \Gamma\left(z_{2}+1\right) \Gamma\left(-\varepsilon-z_{1}\right) \Gamma\left(2 \varepsilon+z_{1}+1\right)\left(-\frac{M_{Z}^{2}}{s}\right)^{z_{1}}}{2 \Gamma\left(1-z_{2}\right) \Gamma\left(-3 \varepsilon-z_{1}+2\right) \Gamma\left(-2 \varepsilon-2 z_{1}-z_{2}\right)} \\
& \times(-s)^{-2 \varepsilon} \Gamma\left(-2 \varepsilon-z_{1}-z_{2}\right)^{2} \Gamma\left(-\varepsilon-z_{1}-z_{2}\right) \Gamma\left(\varepsilon+z_{1}+z_{2}+1\right) \tag{1.14}
\end{align*}
$$

where $\varepsilon=(4-D) / 2$. A straight integration contour parallel to the imaginary axis is chosen, such


Fig. 1: Two-loop vertex Feynman integral with two internal massive lines and the kinematics are $p_{1,2}^{2}=0$ and $2 p_{1} p_{2}=s$. The $Z$-boson mass $M_{Z}$ indicates massive propagators.


Fig. 2: The black dots are the poles of the integrand in Eq. (2.1) in the $z_{1}$ complex plane. The dashed line is the integration contour parallel to the imaginary axis.
that all poles are well separated, see Fig. 2 for $z_{1,2}=-1 / 3+i t, t \in[-\infty, \infty]$. The expansion around $\varepsilon=0$ in Eq. (1.14) leads to a finite contribution in the lowest order:

$$
\begin{gather*}
I_{0 \mathrm{~h} 0 \mathrm{w} 14 \mathrm{r}}=-\int_{-\frac{1}{3}-i \infty}^{-\frac{1}{3}+i \infty} \frac{\mathrm{~d} z_{1}}{2 \pi i} \int_{-\frac{1}{3}-i \infty}^{-\frac{1}{3}+i \infty} \frac{\mathrm{~d} z_{2}}{2 \pi i} \frac{\Gamma\left(-z_{1}\right)^{2} \Gamma\left(z_{1}+1\right) \Gamma\left(-z_{2}\right) \Gamma\left(z_{2}+1\right)\left(-\frac{M_{Z}^{2}}{s}\right)^{z_{1}} \Gamma\left(-z_{1}-z_{2}\right)^{3}}{2 \Gamma\left(2-z_{1}\right) \Gamma\left(1-z_{2}\right) \Gamma\left(-2 z_{1}-z_{2}\right)} \\
\times \Gamma\left(z_{1}+z_{2}+1\right)+\mathscr{O}(\boldsymbol{\varepsilon}) . \tag{1.15}
\end{gather*}
$$

### 1.2 Minkowskian kinematics

Whether we derive the Mellin-Barnes integrals with the loop-by-loop or the global approach, we face problems in the numerical treatment of these integrals in Minkowskian kinematics. To illustrate this we apply the well known Stirling approximation formula

$$
\begin{equation*}
\Gamma(z) \underset{|z| \rightarrow \infty}{\approx} z^{z-1 / 2} e^{-z} \sqrt{2 \pi}, \quad|\arg z|<\pi \tag{1.16}
\end{equation*}
$$

to the integrand in Eq. (1.15) and examine the asymptotic behavior for $z_{1}=-\frac{1}{3}+i t_{1}$, and $z_{2}=$ $-\frac{1}{3}+i t_{2}, t_{1} \rightarrow-t$ and $t_{2} \rightarrow t:$

$$
\begin{equation*}
\left.\mathscr{I}_{0 \mathrm{~h} 0 \mathrm{w} 14 \mathrm{r}} \underset{t \rightarrow \infty}{\approx} t^{-2+2 x_{1}+2 x_{2}}\right|_{x_{1}=x_{2}=-1 / 3} \tag{1.17}
\end{equation*}
$$

In comparison to the Euclidean kinematics, where the asymptotic behavior is everywhere exponentially damped, we see that for Minkowskian kinematics the asymptotic behavior is polynomial. In the case of a Mellin-Barnes integral this polynomial asymptotic behavior leads to numerous numerical instabilities, some of which are:

- Oscillations are less damped compared to the Euclidean case.
- Integrals may be not absolutely convergent if the asymptotic behavior is worse than $1 / t^{a}$, with $a<2$.
- At any level of accuracy, we need to evaluate the integrands for bigger values $t_{i}$ than in the case of Euclidean kinematics.
- In particular, if we are interested in high accuracy results, we have to evaluate the $\Gamma$ functions for very big arguments and this leads again to numerical instabilities.


## 2. Techniques to treat Mellin-Barnes integrals in Minkowskian kinematics

We assume that the treatment of one-dimensional Mellin-Barnes integrals is a solved problem by means of contour deformation. We describe techniques which are applied to multi-dimensional Mellin-Barnes integrals. These techniques are automatized in the Mathematica package MBnumerics, which was developed to treat numerically Feynman integrals appearing in the calculation of the electroweak two-loop corrections to the pseudo observables at the Z-boson resonance [14], [15].

### 2.1 Linear transformation of integration variables

In the case of the Mellin-Barnes integral the linear transformation of integration variables may lead to improvements of the numerical integration. If we apply the variable change $z_{2} \rightarrow z_{2}-z_{1}$ to the example integral in Eq. (1.15) we get

$$
\begin{gather*}
I_{0 h 0 w 14}=-\int_{-\frac{1}{3}-i \infty}^{-\frac{1}{3}+i \infty} \frac{\mathrm{~d} z_{1}}{2 \pi i} \int_{-\frac{2}{3}-i \infty}^{-\frac{2}{3}+i \infty} \frac{\mathrm{~d} z_{2}}{2 \pi i} \frac{\left(-\frac{M_{z}^{2}}{s}\right)^{z_{1}} \Gamma\left(-z_{1}\right)^{2} \Gamma\left(1+z_{1}\right) \Gamma\left(z_{1}-z_{2}\right) \Gamma\left(-z_{2}\right)^{3}}{2 \Gamma\left(2-z_{1}\right) \Gamma\left(-z_{1}-z_{2}\right) \Gamma\left(1+z_{1}-z_{2}\right)} \\
 \tag{2.1}\\
\times \Gamma\left(1+z_{2}\right) \Gamma\left(1-z_{1}+z_{2}\right) .
\end{gather*}
$$

After this simple change of variable the asymptotic behavior of the Mellin-Barnes integrand has been changed. If we apply again the Stirling formula in Eq. (1.16) to the integrand in Eq. (2.1), and study the asymptotic behavior for $z_{1}=-\frac{1}{3}+i t_{1}, z_{2}=-\frac{2}{3}+i t_{2}, t_{1} \rightarrow-t$ and $t_{2} \rightarrow 0$, we find

$$
\begin{equation*}
\left.\mathscr{I}_{0 \mathrm{~h} 0 \mathrm{w} 14} \underset{t \rightarrow \infty}{\approx} t^{-2+2 x_{2}}\right|_{x_{2}=-2 / 3} \tag{2.2}
\end{equation*}
$$

i.e. the polynomial asymptotic behavior depends only on $x_{2}$. Linear integration variable transformations give a possibility for a nontrivial cross check of the numerical evaluation of the MellinBarnes integrals, since the integrands have different asymptotic behavior before and after the linear transformation.

### 2.2 Integrand mappings

An obvious improvement is the application of the cotangent mapping $t=\frac{1}{\tan (-\pi d)}$, which maps the integration boundaries from $t \in[-\infty, \infty]$ to $d \in[0,1]$. We apply this mapping to a polynomial function, which gives

$$
\begin{equation*}
\frac{1}{t^{a}}=\tan (-\pi d)^{a} \tag{2.3}
\end{equation*}
$$

and the Jacobian is:

$$
\begin{equation*}
\frac{\pi}{\sin (\pi d)^{2}}, \tag{2.4}
\end{equation*}
$$

where the limits of the integrand at the boundaries of the new integration domain are:

$$
\lim _{d \rightarrow 0, d \rightarrow 1} \frac{\pi \tan (-\pi d)^{a}}{\sin (\pi d)^{2}}= \begin{cases}\frac{1}{0}, & a<2  \tag{2.5}\\ \pi, & a=2 \\ 0, & a>2\end{cases}
$$

Compared to the cotangent mapping, a logarithmic mapping, as it is advocated in the program MB.m [4], always leads to infinities at the new integration boundaries, which would lead to numerical instabilities.

Since we use the cotangent mapping it is mandatory to transform the integrand as follows:

$$
\begin{equation*}
\prod_{i} \Gamma_{i} \rightarrow \exp \left(\sum_{i} \log \Gamma_{i}\right) \tag{2.6}
\end{equation*}
$$

where the key idea is that the $\log \Gamma\left(z_{i}\right)$ functions grow slower than the $\Gamma\left(z_{i}\right)$ functions for large values of $\left|z_{i}\right|$.

### 2.3 Shifts

If we shift the Mellin-Barnes integration variables according to

$$
\begin{equation*}
z_{i}=x_{i}+i t_{i}+n_{i}, \quad n_{i} \in \mathbb{R}, \tag{2.7}
\end{equation*}
$$

the asymptotic behavior of a given Mellin-Barnes integrand may depend explicitly on the shifts $n_{i}$ :

$$
\begin{equation*}
\left.\mathscr{I}_{0 \mathrm{how} 14} \underset{t \rightarrow \infty}{\approx} t^{-2+2 x_{2}+2 n_{2}}\right|_{x_{2}=-2 / 3} . \tag{2.8}
\end{equation*}
$$

It is then possible to improve the polynomial asymptotic behavior by tuning the shifts $n_{i}$. If, by changing the values of $n_{i}$, the contour crosses some poles of the Mellin-Barnes integrand, we have to collect their residues.

The shifts may also be used as a method to evaluate Mellin-Barnes integrals in Minkowskian regions due to one more observation: the integral along a shifted contour may be numerically smaller by orders of magnitude compared to the original integral.

For example, the original integral in Eq. (2.1), with $M_{Z}=\sqrt{s}=1$, evaluated along the contour $C_{1}$, see Fig. 3, gives $0.3923828588857+0.7456388536613 i$. The shifted integral with $n_{1}=-2$,


Fig. 3: The original contour $C_{1}$ is shifted by $n_{1}=-2$ to a contour $C_{2}$. The third contour $C_{3}$ encircles the poles to correct the shift.
evaluated along the contour $C_{2}$ gives -0.00974965823202 . In addition the following equation holds:

$$
\begin{equation*}
\int \frac{\mathrm{d} z_{2}}{2 \pi i} \int_{C_{1}} \frac{\mathrm{~d} z_{1}}{2 \pi i} \mathscr{I}_{0 \mathrm{~h} 0 \mathrm{w} 14}=\int \frac{\mathrm{d} z_{2}}{2 \pi i} \int_{C_{2}} \frac{\mathrm{~d} z_{1}}{2 \pi i} \mathscr{I}_{0 \mathrm{~h} 0 \mathrm{w} 14}+\overbrace{\int \frac{\mathrm{d} z_{2}}{2 \pi i}\left(\sum_{z_{0}} \operatorname{Res}_{z_{0}} \mathscr{I}_{0 \mathrm{~h} 0 \mathrm{w} 14}\right)}^{1 \text { dim integrals }} . \tag{2.9}
\end{equation*}
$$

We have corrected the result of the integral along the shifted contour by calculating three residues,, corresponding to the three poles enclosed by the contour $C_{3}$. Upon integrating them over $z_{2}$, their sum is $0.402132517117807+0.745638853661318 i$. In general, shifting the contour of an $n$-fold Mellin-Barnes integral will yield residue terms, which will be $(n-1)$-fold Mellin-Barnes integrals and hence simpler to evaluate.

## 3. Nontrivial example

The Feynman integral shown in Fig. 4,

$$
\begin{equation*}
\int \frac{\mathrm{d}^{D} k_{1}}{i \pi^{D / 2}} \frac{\mathrm{~d}^{D} k_{2}}{i \pi^{D / 2}} \frac{\exp \left(2 \varepsilon \gamma_{E}\right) M_{Z}^{2+2 \varepsilon}\left(k_{2} p_{2}\right)}{\left(k_{1}\right)^{2}\left(\left(k_{1}-k_{2}\right)^{2}-m_{t}^{2}\right)\left(\left(k_{2}\right)^{2}-M_{W}^{2}\right)\left(\left(k_{1}+p_{1}\right)^{2}\right)\left(\left(k_{2}+p_{1}\right)^{2}-m_{t}^{2}\right)\left(k_{1}+p_{1}+p_{2}\right)^{2}}, \tag{3.1}
\end{equation*}
$$

depends in a nontrivial way on the scalar product $k_{2} p_{2}$ in the numerator. We evaluate this integral with MBnumerics, which implements the method of the shifts. The results are collected in Tab. 1. The scales are fixed to: $\sqrt{s}=M_{Z}=91.1876 \mathrm{GeV}, M_{W}=80.385 \mathrm{GeV}$ and $m_{t}=173.2 \mathrm{GeV}$. In this example the Mellin-Barnes integral representation is at most a three-dimensional integral. With the sector decomposition approach the Feynman integral (3.1) is five-dimensional. If one can find a Mellin-Barnes integral representation whose integration dimension is smaller than or equal to that of the sector decomposition representation, the method of shifts turns out to be very successful to compute numerically Feynman integrals in Minkowskian regions.


Fig. 4: This Feynman integral depends non-trivially on the scales $s, M_{W}$ and $m_{t}$.

| Method | Numerics |  |
| :--- | :--- | :--- |
| MB | $0.0602664865576999 \varepsilon^{-2}$ |  |
| SD - 90 Mio | $0.06026648655 \varepsilon^{-2}$ |  |
| MB | $(-0.0315124890$ | $+0.1893327514 i) \varepsilon^{-1}$ |
| SD - 90 Mio | $(-0.031512481$ | $+0.189332716 i) \varepsilon^{-1}$ |
| MB | $(-0.22823186755$ | $-0.08824794573 i)+\mathscr{O}(\varepsilon)$ |
| SD - 90 Mio | $(-0.2282265$ | $-0.0882459 i)+\mathscr{O}(\varepsilon)$ |

Tab. 1: The numbers labeled MB are evaluated with MBnumerics. The numbers labelled with SD are evaluated with SecDec v. 3 [16].

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