

The performance of the MAGIC telescopes using deep convolutional neural networks with CTLearn

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The Major Atmospheric Gamma Imaging Cherenkov (MAGIC) telescope system is located on the Canary Island of La Palma and inspects the very high-energy (VHE, few tens of GeV and above) gamma-ray sky. MAGIC consists of two imaging atmospheric Cherenkov telescopes (IACTs), which capture images of the air showers originating from the absorption of gamma rays and cosmic rays by the atmosphere, through the detection of Cherenkov photons emitted in the shower. The sensitivity of IACTs to gamma-ray sources is mainly determined by the ability to reconstruct the properties (type, energy, and arrival direction) of the primary particle generating the air shower. The state-of-the-art IACT pipeline for shower reconstruction is based on the parameterization of the shower images by extracting geometric and stereoscopic features and machine learning algorithms like random forest or boosted decision trees. In this contribution, we explore deep convolutional neural networks applied directly to the pixelized images of the camera as a promising method for IACT full-event reconstruction and present the performance of the method on observational data using CTLearn, a package for IACT event reconstruction that exploits deep learning.

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1. Introduction

In this contribution, we show how deep convolutional neural networks (CNNs) can be utilized to detect astrophysical gamma-ray sources like the Crab Nebula using CTLearn¹ [1–4], a deep learning (DL) framework for IACT event reconstruction, and DL1-Data-Handler² (DL1DH) [5], a package designed for the data management of machine learning image analysis techniques for IACT data. The results are compared to the standard analysis (random forest (RF) for the background rejection, Look-Up tables (LUTs) for the energy estimation and RF for bidimensional direction reconstruction) obtained with MAGIC Analysis and Reconstruction Software MARS [6, 7]. Previous DL analyses of MAGIC data [8] were carried out with CTLearn v0.5 based on TensorFlow³ v1, while this work used CTLearn v0.6, which adopted the Keras⁴ API [9] from TensorFlow v2 [10].

The workflow of the MAGIC DL analysis with CTLearn is illustrated in Fig. 1. First, the images are calibrated and cleaned by MARS to suppress the major fraction of the Night Sky Background (NSB). Crucial information are translated into uproot⁵-readable branches [11] using a complementary macro. Then, the DL1DH assembles several data levels from MARS and unifies them in a common data format in HDF5 designed for DL purposes. The image preprocessing and data reading is managed by the DL1DH. Bilinear interpolation is used to map the hexagonal pixel layout of the MAGIC cameras to a Cartesian lattice to directly apply CNNs [12]. Finally, CTLearn performs training and prediction with CNN-based models, allowing for full-event reconstruction.

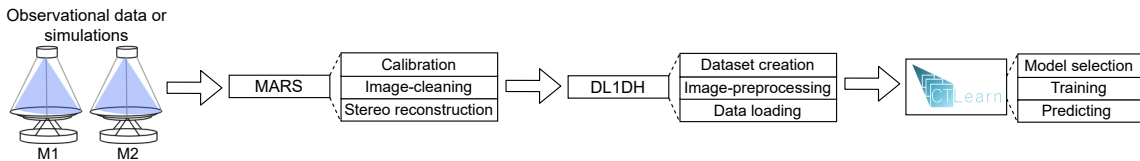


Figure 1: Workflow of the MAGIC DL analysis with CTLearn [8].

2. DL analysis with the MAGIC telescopes

2.1 Model selection

For this work, we selected CTLearn’s Thin-ResNet (TRN) [15] model [13, 14], which is a shallow residual neural network [16] with 33 layers⁶. In each of the residual blocks, we deploy a dual squeeze-and-excitation (SE) attention mechanism [17] to focus on the channel relationship. We perform either particle classification or regression (energy or arrival direction reconstruction) with a fully-connected head (FCH), a traditional multi-layer perceptron (MLP) neural network. The properties (type, energy, and arrival direction) of the primary particle generating the air

¹<https://github.com/ctlearn-project/ctlearn>

²<https://github.com/cta-observatory/dl1-data-handler>

³<https://www.tensorflow.org/>

⁴<https://keras.io/>

⁵<https://github.com/scikit-hep/uproot4>

⁶The first initialization layer of the original Thin-ResNet [15] is skipped in order to adjust for the specific input shape of the MAGIC images.

shower are reconstructed in the single-task learning mode (see [18] for an IACT-based multi-task learning architecture), where each task is trained with a separate network. We explore stereoscopic information by concatenating the images (integrated pixel charges and signal arrival times) of the two MAGIC telescopes channel-wise before feeding the network as depicted in Fig. 2.

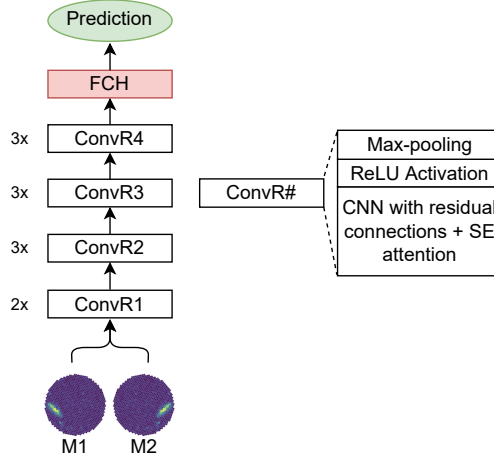


Figure 2: CTLearn’s TRN model with channel-wise concatenation of the two stereoscopic images recorded by the MAGIC telescopes (M1 and M2).

2.2 Validation on simulations

The evaluation of the performance using common metrics like ROC curves, energy and angular resolution curves with the same quality cuts (see Fig. 3) are taken from [8]. A similar performance is also observed with CTLearn v0.6. Monte Carlo (MC) gamma simulations coming uniformly from a 0.4° offset of the telescope pointing (ringwobble) are used to obtain the reconstruction performance. For the background rejection (see *left panel* of Fig. 3), we tested against MC proton simulations and observational off-source data, where we do not expect any gamma-ray signal.

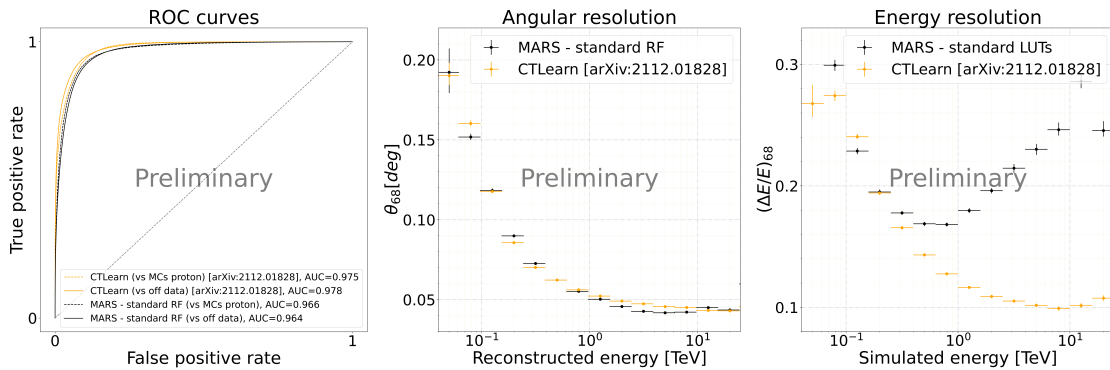


Figure 3: The validation of the performance is taken from [8]. *Left*) ROC curves with MC proton simulations and observational off data. *Center*) Angular resolution vs. reconstructed energy. *Right*) Energy resolution vs. simulated energy.

2.3 Results on observational data

We analyzed 5.38 h of observations of the standard gamma-ray candle the Crab Nebula, taken with the MAGIC telescopes on four different nights in 2016 under good weather conditions at low zenith distance ($z_d < 35^\circ$). We used MARS and CTLearn with two settings of analysis cuts (in background suppression and reconstructed energy) focusing on the medium energy (ME; $E > 250$ GeV) and low energy (LE; $E > 100$ GeV) range. For a fair comparison between the different analysis methods, the background (bkg) rates of the CTLearn analyses are adjusted, through a fine-tuning of the background suppression cut, to match for the corresponding standard MARS analyses (ME or LE). The Crab Nebula is detected using θ^2 plots (see Fig. 4 for the CTLearn ME analysis), where θ is the angular separation of the source position and the reconstructed arrival direction of the very high-energy photon. The main results of all analyses are summarized in Tab. 1. The same arrival direction cuts, which defines the fiducial gamma-ray signal region in the θ^2 plots, are applied to all different analysis methods. Three off-source positions are considered to evaluate the background distributions. The sensitivity is computed as the strength of the source that gives $\text{excess}/\sqrt{\text{background}} = 5$ after 50h with the condition of $\text{excess}/\text{background} > 5\%$ and is given in percentage of the Crab Nebula flux. The significance is calculated following Li&Ma [19].

Analysis	N_{on}	N_{off}	N_{ex}	γ rate [/min]	bkg rate [/min]	Sen. [% Crab]	Sig. (Li&Ma)
MARS – ME	1934	45.3 ± 3.9	1888.7 ± 44.1	5.85 ± 0.14	0.140 ± 0.012	0.58 ± 0.03	66.6σ
CTLearn – ME	1907	46.0 ± 3.9	1861.0 ± 43.8	5.77 ± 0.14	0.143 ± 0.012	0.60 ± 0.03	66.0σ
MARS – LE	7933	1827.3 ± 24.7	6105.7 ± 92.4	18.91 ± 0.29	5.661 ± 0.076	1.50 ± 0.01	83.7σ
CTLearn – LE	7889	1826.3 ± 24.7	6062.7 ± 92.2	18.78 ± 0.29	5.658 ± 0.076	1.51 ± 0.01	83.2σ

Table 1: Summary of all performed analyses (LE/ME and MARS/CTLearn) of the same Crab Nebula sample.

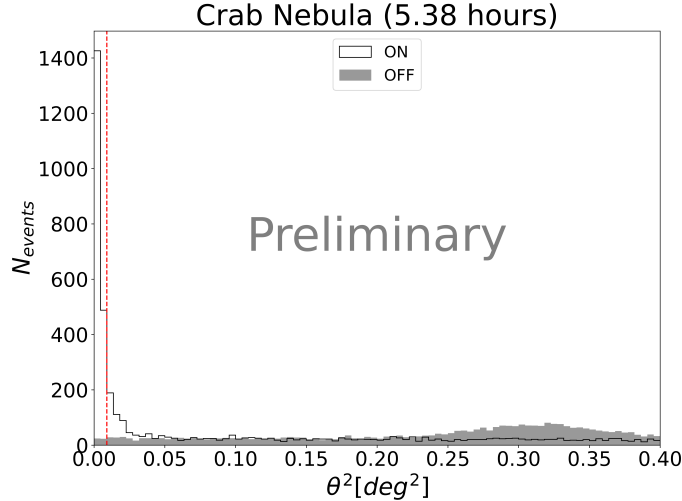


Figure 4: θ^2 plot for the CTLearn ME analysis.

3. Conclusions and outlook

This contribution shows that CNN-based full-event reconstruction works for MC simulations and observational data of the MAGIC telescopes. The performance obtained with CTLearn v0.6 matches the sensitivity of detection of the conventional analysis on real data. The selected TRN model is relatively shallow and further performance enhancements are foreseen by increasing the model depth/complexity. We plan to evaluate the full performance of the MAGIC telescopes with CNN-based analyses under various observation conditions in the future.

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