



Implications of gradient flow on the static force

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We use gradient flow to compute the static force based on a Wilson loop with a chromoelectric field insertion. The result can be compared on one hand to the static force from the numerical derivative of the lattice static energy, and on the other hand to the perturbative calculation, allowing a precise extraction of the Λ_0 parameter. This study may open the way to gradient flow calculations of correlators of chromoelectric and chromomagnetic fields, which typically arise in the nonrelativistic effective field theory factorization.

The 39th International Symposium on Lattice Field Theory, 8th-13th August, 2022, Rheinische Friedrich-Wilhelms-Universität Bonn, Bonn, Germany

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1. Introduction

The static energy E(r) of a quark-antiquark pair is one of the first quantities computed in lattice QCD; the static force is its derivative. At short distances it can be compared to perturbative calculations, and therefore, it can be used for extracting the strong coupling constant. Furthermore, it can be used to set the scale on the lattice.

The static energy is perturbatively known up to N³LL [1–5] and, hence, so it is the force F(r). However, the perturbative static energy in dimensional regularization has a renormalon ambiguity of order Λ_{QCD} , which corresponds to a linear UV divergence ($\propto 1/a$) on the lattice. This ambiguity and divergence vanish if we take the derivative for obtaining the static force, and all the physical information, like the coupling, is encoded in the slope of the static energy.

Recently, the force has been measured on the lattice directly [6], and perturbatively calculated at NLO in continuum in $\overline{\text{MS}}$ with gradient flow [7]. The present work is based on both developments and presents updates with respect to previous results [8]. We find it useful to use the derivative of the static energy as a benchmark to assess discretization effects and systematics. This work is also instrumental to set best strategies to calculate on the lattice chromoelectric and chromomagnetic field correlators arising in the nonrelativistic effective field theories low energy factorization. The study is sufficiently innovative to grant interest even if quenched.

The proceedings are organized as follows. In Sec. 2 we introduce the definition of the force in terms of a chromolectric insertion in a static Wilson loop, the gradient flow, the flowed force and the lattice setup. In Sec. 3, we present the analysis of the lattice data, the continuum limit and the comparison to the perturbative results in the short range.

2. Physical setup

2.1 The static force

The static energy E(r) is related to a Wilson loop $W_{r\times T}$ with temporal extent from 0 to T and spatial extent r [9] by

$$E(r) = -\lim_{T \to \infty} \frac{\ln\langle \operatorname{Tr}(W_{r \times T}) \rangle}{T} = -\frac{1}{a} \lim_{T \to \infty} \frac{\langle \operatorname{Tr}(W_{r \times (T+a)}) \rangle}{\langle \operatorname{Tr}(W_{r \times T}) \rangle}, \tag{1}$$

$$W_{r\times T} = P\left\{\exp\left(i\oint_{r\times T} dz_{\mu}gA_{\mu}\right)\right\},\tag{2}$$

where *a* is the lattice spacing, and *P* is the path ordering operator. The static force F(r) is defined as the derivative of the static energy:

$$F(r) = \partial_r E(r). \tag{3}$$

Often, this derivative is evaluated from the static energy data either with interpolations or with finite differences. However, this leads to increased systematic errors. Alternatively, we can measure the force on the lattice directly via the formula [10–12]

$$F(r) = -\lim_{T \to \infty} \frac{i}{\langle \operatorname{Tr}(W_{r \times T}) \rangle} \left\langle \operatorname{Tr} \left(P \left\{ \exp\left(i \oint_{r \times T} dz_{\mu} g A_{\mu} \right) \mathbf{\hat{r}} \cdot g \mathbf{E}(\mathbf{r}, t^{*}) \right\} \right) \right\rangle$$
(4)

$$= -\lim_{T \to \infty} i \frac{\langle \operatorname{Ir}\{PW_{r \times T}gE_{j}(\mathbf{r}, t^{*}) \rangle}{\langle \operatorname{Tr}(W_{r \times T} \rangle)}, \qquad (5)$$

where the expression in the numerator consists of a static Wilson loop with a chromoelectric field insertion on the temporal Wilson line at position t^* , and $\hat{\mathbf{r}}$ is the spatial direction. In general, t^* is arbitrary. Nevertheless, we choose $t^* = T/2$ for even-spaced separations, and an average over $t^* = T/2 \pm a/2$ for odd-spaced separations. This reduces the interactions between the *E*-field and the corners of the Wilson loop.

2.2 Gradient flow

The Yang-Mills gradient flow flows the gauge fields U_{μ} towards the minimum of the Yang-Mills gauge action along a fictitious dimension called flow time τ_F . The transformation is determined by solving the ordinary differential equation for flowed link variables with the original configuration as initial condition [13–15]:

$$\dot{V}_{\tau_F}(x,\mu) = -g_0^2 \left[\partial_{x,\mu} S(V_{\tau_F})\right] V_{\tau_F}(x,\mu),\tag{6}$$

$$V_{\tau_F}(x,\mu)|_{\tau_F=0} = U_{\mu}(x),$$
(7)

where $\partial_{x,\mu}S(V_{\tau_F})$ is the derivative of a gauge action according to the flowed link variable $V_{\tau_F}(x,\mu)$. It is known that gradient flow acts like smearing characterized by the flow radius $\sqrt{8\tau_F}$, which improves the signal to noise ratio and renormalizes gauge invariant operators. This is especially useful for operators with field strength component insertions, which would normally require an extra renormalization on the lattice.

The flowed link variable depends only on the initial configuration, therefore, we can write it as a function of the non-flowed field as $V_{\tau_F} = V_{\tau_F}[U]$. Flowed observables are obtained by replacing the original gauge links with the flowed ones, the resulting path integral is represented as

$$\langle O(\tau_F) \rangle = \frac{1}{Z} \int \mathcal{D}[U] e^{-S_E[U]} O[V_{\tau_F}], \qquad (8)$$

which states that the underlying theory remains unchanged. However, to connect to the physical observable, we have to perform the limit $\tau_F \rightarrow 0$.

2.3 The perturbative force in gradient flow

The static force in gradient flow has been perturbatively determined at 1-loop order in Ref. [7] for general flow time τ_F . In the small flow time expansion, it can be expressed as

$$r^{2}F^{1-\text{loop}}(r,\tau_{F}) \approx r^{2}F^{1-\text{loop}}(r,\tau_{F}=0) + \frac{\alpha_{S}^{2}C_{F}}{2\pi} \underbrace{\left[-12\beta_{0}-6C_{A}c_{L}\right]}_{8n_{f}} \frac{\tau_{F}}{r^{2}},\tag{9}$$

with $c_L = -22/3$. We see that, in pure gauge, the static force should be constant for small flow times, since the flow time dependent term is proportional to n_f . Furthermore, the relevant scale for the force is the dimensionless ratio τ_F/r^2 . We note that in the analysis, the flow time τ_F and the flow time ratio τ_F/r^2 can be used interchangeably. The whole 1-loop expression can be found in [7].

Since the static force is known to 3-loop order at zero flow time and the higher loop contributions are crucial for the extraction of the Λ_0 parameter, we choose a hybrid ansatz, where we model the

N_S	N_T	β	<i>a</i> [fm]	Nconf	Label
20	40	6.284	0.060	6000	L20
26	52	6.481	0.046	6000	L26
30	60	6.594	0.040	6000	L30
40	80	6.816	0.030	2700	L40

Table 1: The lattice parameters for the computations.

flow time dependence with the full 1-loop formula and use the higher loop result at zero flow time. Up to a given order:

$$r^2 F^{\text{order}}(r, \tau_F) \equiv r^2 F^{\text{order}}(r, \tau_F = 0) + f^{1-\text{loop}}(r, \tau_F)$$
(10)

$$f^{1-\text{loop}}(r,\tau_F) \equiv r^2 F^{1-\text{loop}}(r,\tau_F) - r^2 F^{1-\text{loop}}(r,\tau_F=0).$$
(11)

We work in the pure SU(3) gauge theory $(n_f = 0)$, and call $\Lambda_0 \equiv \Lambda_{\overline{MS}}^{n_f=0}$. In Ref [7], they discuss the scale choices of $\mu = 1/r$, $\mu = 1/\sqrt{r^2 + 8\tau_F}$, and $\mu = 1/\sqrt{8\tau_F}$. We will focus on $\mu = 1/r$ and $\mu = 1/\sqrt{r^2 + 8\tau_F}$ here.

2.4 Lattice setup

We generate quenched gauge field configurations with the MILC code. Table 1 shows the parameters used in our calculations. The scale setting is done through [16]. The configurations are produced with overrelaxation and heatbath algorithm. For solving the gradient flow equation, we use the Symanzik improved action, and fixed stepsize algorithm [15] for the lattices L20, L26, and L30, and adaptive algorithm for L40 [17, 18]. We use blocking with jackknife sampling for the error propagation.

3. Analysis

3.1 Plateau extraction

In order to extract the ground state of the static force and energy in the $T \to \infty$ limit, we fit a constant within a suitable range of T. This has to be done for each fixed (r, τ_F) or $(r, \tau_F/r^2)$ at each lattice. We automatize the plateau extraction with the Akaike information criterion (AIC) based model averaging, as described in Ref. [19].

Here, we will briefly summarize the model averaging procedure. We are interested in the model parameters $\mathbf{a} \in \mathbb{R}^k$ (k being the number of parameters) of a model function $f(x, \mathbf{a})$ for a quantity x_i with i = 1, ..., N. We have the data $D = (x_i, y_i, C_{ij})$ with y_i being the data corresponding to x_i , and C_{ij} its covariance matrix. We perform the fits using the data only in the range i_1 to i_2 for all possible ranges between 1, ..., N, and $i_2 - i_1 > 3$ fixed. Every fit has a set of optimal parameters $\mathbf{a}^*_{i_1,i_2}$ and an optimal χ^2 -value which leads us to the information criterion

$$AIC_{i_1,i_2} = \sum_{i,j=i_1}^{i_2} \left[f(x_i, \mathbf{a}^{\star}_{i_1,i_2}) - y_i \right] C_{ij}^{-1} \left[f(x_j, \mathbf{a}^{\star}_{i_1,i_2}) - y_j \right] + 2k + 2(i_1 - i_2),$$
(12)

which defines the model probability

$$p(i_1, i_2|D) \propto e^{-\frac{1}{2}\operatorname{AIC}_{i_1, i_2}}$$
 (13)

Finally, we are interested in a specific component of the parameter vector, and we can determine the expectation value and the standard deviation as

$$\overline{a}_n = \langle a_n \rangle = \sum_{i_1, i_2} a^{\star}_{n, i_1, i_2} p(i_1, i_2 | D), \tag{14}$$

$$\sigma_n^2 = \left\langle (a_n - \overline{a}_n)^2 \right\rangle = \left\langle a_n^2 \right\rangle - \left\langle a_n \right\rangle^2 \,. \tag{15}$$

For the specific case of constant fit, we have one parameter (k = 1), the constant *c*, the support points of *T* correspond to x_i , and the model function *f* is the constant function f(T, c) = c.

For our analysis, we measure the AIC expectation value for each jackknife pseudoensemble separately, and then use the jackknife errors for the standard deviation. The error given by the jackknife procedure is comparable to the model uncertainty of Eq. (15).

3.2 Impact of the gradient flow

For the static force, the chromoelectric field inserted to a Wilson loop comes with a lattice only self-energy contribution that needs to be renormalized away in order to attain a proper continuum limit. The renormalization is multiplicative and independent of the distance *r*:

$$F_{\text{latt}}^{\text{ren}}(r,\tau_F) = Z_E(\tau_F)F_{\text{latt}}(r,\tau_F).$$
(16)

 Z_E can be non-perturbatively determined by comparing F_{latt} to a numerical derivative of the static energy, which does not include field insertions [6]:

$$Z_E(\tau_F) = \frac{\partial_r V_{\text{latt}}(r, \tau_F)}{F_{\text{latt}}(r, \tau_F)} \,. \tag{17}$$

We extract Z_E at fixed flow time by performing a constant fit within an intermediate *r*-range, that is not affected by finite size or finite volume effects. We use the AIC model averaging for these fit ranges as described in Sec. 3.1. The left side of Fig. 1 shows Z_E for the different lattice sizes, the *x*-axis is in units of the flow radius in lattice units. We see that, for flow radii larger than one lattice spacing ($\sqrt{8\tau_F} \gtrsim a$), Z_E approaches 1, meaning that gradient flow reduces effectively the discretization artifacts. This allows us to perform reliable continuum limits at finite flow time. We consider continuum limit data only for flow times satisfying the condition $\sqrt{8\tau_F}/a \gtrsim 1$. An example for a continuum limit is shown on the right side of Fig. 1.

3.3 Static force at large r

According to Eq. (9), we expect a constant behavior in the small flow time ratio expansion. The left side of Fig. 2 shows the force at large fixed r. We see a constant regime within the range $0.01 \le \tau_F/r^2 \le 0.025$ and we use AIC as described in Sec. 3.1 to consider all meaningful ranges to reduce the systematic errors arising from the choice of the fit range. The results of the constant fit are shown on the right side of Fig. 2. The figure shows the results of three different methods;



Figure 1: Left: The non-perturbative determination of the flowed renormalization constant Z_E . Right: An example for a continuum limit where $Z_E \approx 1$.



Figure 2: Left: The flowed force at fixed r, for large r. The x-axis is the flow time ratio. Right: The results of the constant fits within a reliable flow time range.

they differ by interpolation functions and whether the continuum limit was performed at fixed flow time or flow time ratio. All methods should give the same results, however, we see deviations at larger r indicating the size of the systematic errors. We fit the Cornell ansatz

$$r^2 F(r) = A + \sigma r^2 \tag{18}$$

to the result, with σ being the string tension. We obtain σ between 5.18 fm⁻² and 5.23 fm⁻² and A between 0.2853 and 0.2954. We note that the distances achievable with our lattice sizes are too small for reliable measurement of the string tension.

3.4 Static force at small r

The left side of Fig. 3 shows the force at fixed small r against the flow time ratio. The dimmer points at smaller flow time ratio belong to the regime where $Z_E \neq 1$. We fit Eq. (10) treating Λ_0 as the fit parameter to the valid data. For the three cases shown on the left side in Fig. 3, we obtain a range of Λ_0 between 0.238 and 0.256 GeV. The scale choice $\mu = 1/r$ fits best to our measured data in this case.

Instead of fitting to data at fixed r, we can fit to fixed τ_F along the *x*-axis. It turns out that this procedure works better for fixed flow time than for fixed flow time ratio. The right side of Fig. 3



Figure 3: Fitting the perturbative force (dashed lines) to the data (crosses and errorbars) at small *r*. Left: Fit for fixed *r*, the dimmer points represent the points where not enough flow time was applied and therefore, $Z_E \neq 1$. Those points are excluded from the fits. Right: Fit for a fixed *r*-range at three different exemplary flow times. In all fits, Λ_0 is the fit parameter.



Figure 4: The results for the Λ_0 fits at fixed *r* for different flow times (x-axis). Left: The result at fixed *r*-range. Right: The model averaged result for Λ_0 with averaging over different *r*-ranges. The solid lines show the zero flow time extrapolation.

shows the fit at three different fixed flow times, the left side of Fig. 4 shows the resulting Λ_0 at finite τ_F for two scale choices. Both choices seem to exhibit a linear flow time behavior in a proper range of flow time. We can assume a linear ansatz within the linear regime and perform a zero flow time limit for Λ_0 which gives $\Lambda_0 = 0.262$ GeV and $\Lambda_0 = 0.261$ GeV respectively. This is close to the Λ_0 from FLAG [20] with $\Lambda_0^{\text{FLAG}} = 261(15)$ MeV. We should not see any flow time dependence on Λ_0 . Therefore, the flow time dependence, we observe in Fig. 4, must arise either from corrections at higher orders of perturbation theory or from systematic effects in the chosen analysis.

Instead of a fixed *r*-range, we can use the AIC procedure from Sec. 3.1 to find an optimal range for the Λ_0 -fit. The resulting Λ_0 -values as a function of the flow time are shown on the right side of Fig. 4 for different orders of perturbation theory used for the zero flow time part of Eq. (10). We observe, that in the range $0.08 \le \tau_F / a_{20}^2 \le 0.18$, the flow time dependence of Λ_0 can be described by a constant within the error bars. Using a constant fit to extrapolate to the zero flow time limit, we find the values for Λ_0 at 1-, 2-, and 3-loops with ultrasoft logs resummed to be 0.297 GeV, 0.264 GeV, and 0.253 GeV respectively. Our result is consistent with the value 0.251(12) GeV that was measured from the pure gauge static potential in Ref. [21]. We leave the full error analysis of these results to a future publication [22].

Acknowledgments

The lattice QCD calculations have been performed using the publicly available MILC code. The simulations were carried out on the computing facilities of the Computational Center for Particle and Astrophysics (C2PAP) in the project 'Calculation of finite T QCD correlators' (pr83pu) and of the SuperMUC cluster at the Leibniz-Rechenzentrum (LRZ) in the project 'The role of the charm-quark for the QCD coupling constant' (pn56bo). This research was funded by the Deutsche Forschungsgemeinschaft (DFG, German Research Foundation) cluster of excellence "ORIGINS" (www.origins-cluster.de) under Germany's Excellence Strategy EXC-2094-390783311.

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